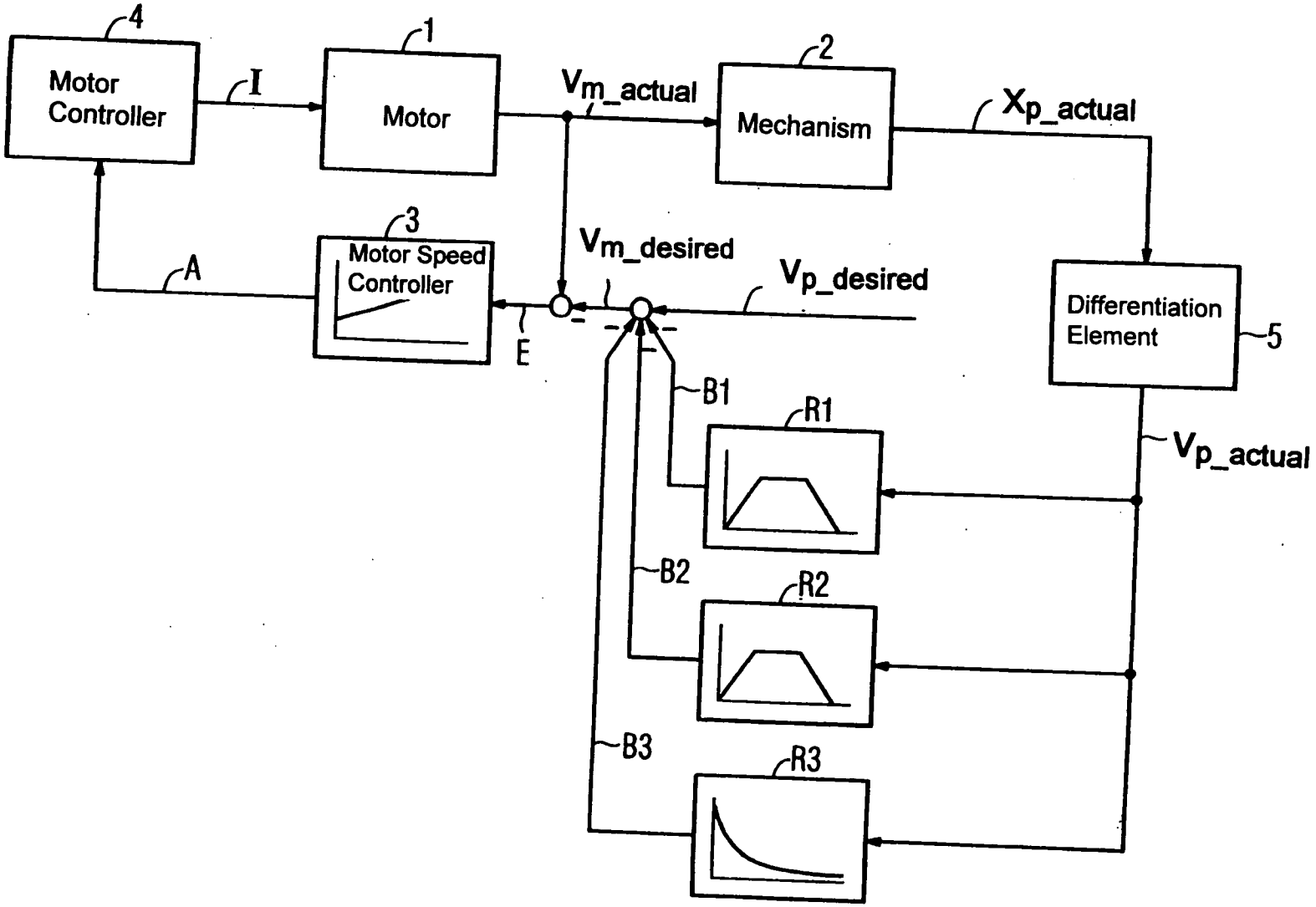
4
Motor Controller
I
1
Motor
Vm_actual
2
Mechanism
Xp_actual
3
Motor Speed Controller
A
Vm_desired
Vp_desired
E
Differentiation Element
5
B1
R1
Vp_actual
B2
R2
B3
R3